Data sheet



SIMATIC DP, CPU 1516pro-2 PN for ET 200pro, central processing unit with 2 MB work memory for program and 7.5 MB for data, 1st interface: PROFINET IRT with 3-port switch, 2nd interface: PROFINET RT, 6 ns bit performance, degree of protection: IP65/67, SIMATIC Memory Card required, connection module required

Figure similar

General information	
Product type designation	CPU 1516pro-2 PN
HW functional status	FS01
Firmware version	V3.1
FW update possible	Yes
Product function	
I&M data	Yes; I&M0 to I&M3
 Isochronous mode 	Yes; Via X1, with minimum OB 6x cycle of 500 μs
SysLog	Yes
Engineering with	
STEP 7 TIA Portal configurable/integrated from version	V19 (FW V3.1); with older TIA Portal versions configurable as 6ES7516-2PN00-0AB0
Configuration control	
via dataset	No
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	20.4 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms
Input current	
Current consumption (rated value)	0.22 A
Current consumption, max.	0.35 A
Inrush current, max.	0.63 A; Rated value
l²t	0.3 A ² ·s
from supply voltage 1L+, max.	0.35 A
Power	
Infeed power to the backplane bus	2.275 W
Power loss	
Power loss, typ.	3.3 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	2 Mbyte
• integrated (for data)	7.5 Mbyte

Load memory	
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	50,10
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	6 ns
for word operations, typ.	7 ns
for fixed point arithmetic, typ.	9 ns
for floating point arithmetic, typ.	37 ns
CPU-blocks	Of the
Number of elements (total)	8 000; Blocks (OB, FB, FC, DB) and UDTs
DB	6 000, Blocks (OB, FB, FO, DB) and OD 15
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	7.5 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	
Number range	0 65 535
• Size, max.	1 Mbyte
FC	
Number range	0 65 535
• Size, max.	1 Mbyte
OB	
• Size, max.	1 Mbyte
 Number of free cycle OBs 	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
 Number of cyclic interrupt OBs 	20; With minimum OB 3x cycle of 250 µs
 Number of process alarm OBs 	50
 Number of DPV1 alarm OBs 	3
 Number of isochronous mode OBs 	1
 Number of technology synchronous alarm OBs 	2
 Number of startup OBs 	100
 Number of asynchronous error OBs 	4
 Number of synchronous error OBs 	2
 Number of diagnostic alarm OBs 	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
 Number 	2 048
Retentivity	
— adjustable	Yes
IEC counter	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	512 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 472 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
- Namber of clock memories	

Retentivity adjustable	Yes
Retentivity adjustable Retentivity preset	No
Local data	
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	o riabito, mais to the polibiook
Number of IO modules	8 192; max. number of modules / submodules
I/O address area	o 102, max. namber of modulos / cabinedates
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Hardware configuration	
Number of distributed IO systems	64; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of IO Controllers	
• integrated	2
• Via CM	0
Rack	
 Modules per rack, max. 	16; Expansion width max. 1.2 m
Number of lines, max.	1
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• in AS, master	Yes
• in AS, device	Yes
on Ethernet via NTP Interfaces	Yes
Interfaces Number of PROFINET interfaces	2
Number of PROFINET interfaces	2
Number of PROFIBUS interfaces 1. Interface	0
Interface types	Voc. V1 P2
RJ 45 (Ethernet) Number of ports	Yes; X1 P3
Number of ports integrated switch	3; 2x M12 + 1x RJ45 Yes
integrated switch Protocols	1 63
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Controller PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
Prioritized startup	Yes; Max. 32 PROFINET devices
Number of connectable IO Devices, max.	256; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Of which IO devices with IRT, max.Number of connectable IO Devices for RT, max.	64 256

- of which in line, max. 256 Number of IO Devices that can be simultaneously 8; in total across all interfaces activated/deactivated, max. - Number of IO Devices per tool, max. — Updating times The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data - PROFINET Security Class Update time for IRT $250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum — for send cycle of 250 µs update time of 500 μs of the isochronous OB is decisive — for send cycle of 500 µs 500 us to 8 ms - for send cycle of 1 ms 1 ms to 16 ms - for send cycle of 2 ms 2 ms to 32 ms - for send cycle of 4 ms 4 ms to 64 ms — With IRT and parameterization of "odd" send cycles Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s ... 3 Update time for RT — for send cycle of 250 μs 250 µs to 128 ms — for send cycle of 500 µs 500 µs to 256 ms - for send cycle of 1 ms 1 ms to 512 ms - for send cycle of 2 ms 2 ms to 512 ms - for send cycle of 4 ms 4 ms to 512 ms **PROFINET IO Device** Services Isochronous mode Nο - IRT — PROFlenergy Yes; per user program - Shared device Yes - Number of IO Controllers with shared device, max. - activation/deactivation of I-devices Yes; per user program Asset management record Yes; per user program - PROFINET Security Class SNMP Configuration and DCP Read Only Interface types • RJ 45 (Ethernet) No Number of ports 1; 1x M12 • integrated switch Nο Protocols • IP protocol Yes: IPv4 • PROFINET IO Controller Yes • PROFINET IO Device Yes • SIMATIC communication Yes • Open IE communication Yes; Optionally also encrypted Web server Yes Media redundancy No **PROFINET IO Controller** Services - Isochronous mode No Nο - Direct data exchange — IRT — PROFlenergy Yes; per user program - Prioritized startup - Number of connectable IO Devices, max. 32; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET - Number of connectable IO Devices for RT, max. 32 - of which in line, max — Number of IO Devices that can be simultaneously 8: in total across all interfaces activated/deactivated, max. - Number of IO Devices per tool, max. - Updating times The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data

DD OFWET O II O	
— PROFINET Security Class	1
Update time for RT	4 4 740
— for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services	
— Isochronous mode	No
— IRT	No
— PROFlenergy	Yes; per user program
 Prioritized startup 	No
— Shared device	Yes
 Number of IO Controllers with shared device, max. 	4
 activation/deactivation of I-devices 	Yes; per user program
 Asset management record 	Yes; per user program
 — PROFINET Security Class 	SNMP Configuration and DCP Read Only
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
 Autocrossing 	Yes
Industrial Ethernet status LED	Yes
Protocols	
PROFIsafe	No
Number of connections	
Number of connections, max.	128; Via integrated interfaces of the CPU
Number of connections reserved for ES/HMI/web	10
 Number of connections via integrated interfaces 	128
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
Media redundancy	Yes; only via 1st interface (X1)
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
- MRP interconnection, supported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
 Switchover time on line break, typ. 	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
S7 communication, as server	Yes
S7 communication, as server S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	535 S.IIIIO TOP (57 SSTITIATIONION, NOOT WILL SIZE)
• TCP/IP	Yes
— Data length, max.	64 kbyte
several passive connections per port, supported	Yes
ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
■ Data length, max. ■ UDP	Yes
■ Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— Data length, max. — UDP multicast	Yes; max. 118 multicast circuits
DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
M/-b	
Web server	Very Oter dead and services and
Web server • HTTP • HTTPS	Yes; Standard and user pages Yes; Standard and user pages

• web API	
Number of sessions, max.	100
— number of simultaneous HTTP calls, max.	4
— HTTP request body, max.	131 072 byte
OPC UA	1010120,10
Runtime license required	Yes; "Medium" license required
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call
Application authentication	Yes
Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15,
	Basic256Sha256
— User authentication	"anonymous" or by user name & password
— Number of connections, max.	10
 Number of nodes of the client interfaces, recommended max. 	2 000
 Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_L max. 	300
 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 Number of simultaneous calls of the client instructions for session management, per connection, max. 	1
 Number of simultaneous calls of the client instructions for data access, per connection, max. 	5
Number of registerable nodes, max.	5 000
Number of registerable method calls of	100
OPC_UA_MethodCall, max.	
 Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data Access (Read, Write, Subscribe), Method Call, Alarms & Condition (A&C), Custom Address Space
 Application authentication 	Yes
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
— User authentication	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
— Number of sessions, max.	48
 Number of accessible variables, max. 	100 000
 Number of registerable nodes, max. 	20 000
Number of subscriptions per session, max.	50
— Sampling interval, min.	100 ms
— Publishing interval, min.	100 ms
Number of server methods, max.	50
Number of server methods, max. Number of inputs/outputs per server method, max.	20
Number of imputs/outputs per server metriou, max. Number of monitored items, recommended max.	4 000; for 1 s sampling interval and 1 s send interval
 — Number of server interfaces, max. — Number of nodes for user-defined server interfaces, 	10; or 20, depending on type of server interface 30 000
max.	
 Alarms and Conditions 	Yes
— Number of program alarms	200
 Number of alarms for system diagnostics 	100
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
number of subscriptions, max.	500
number of tags/attributes for subscriptions, max.	8 000
Program alarms	Yes
Number of configurable program messages, max.	10 000; Program messages are generated by the "Program_Alarm" block,
Number of loadable program messages in RUN, max.	ProDiag or ĞRAPH 10 000
Number of simultaneously active program alarms	
Number of program alarms	1 000
- Hamber of program dialins	1 000

	200
Number of alarms for system diagnostics Number of alarms for motion technology chicate	200
Number of alarms for motion technology objects	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Profiling	Yes
Status/control	
Status/control variable	Yes
 Variables 	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
 Number of variables, max. 	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
Forcing	Yes
• Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
Number of entries, max.	3 200
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4
Memory size per trace, max.	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
 Monitoring of the supply voltage (PWR-LED) 	Yes; green "24 V DC" LED
Connection display LINK TX/RX	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of axes affects the cycle time of the PLC program;
 Number of available Motion Control resources for technology objects 	selection guide via the TIA Selection Tool or SIZER 2 400
Required Motion Control resources	
— per speed-controlled axis	40
— per positioning axis	80
— per synchronous axis	160
— ner external encoder	
per external encoder	80
— per external encoder — per output cam	80 20
·	
— per output cam	20
— per output cam — per cam track	20 160
 per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	20 160
 per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle 	20 160 40
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	20 160 40
 per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) 	20 160 40
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	20 160 40 11 20
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact	20 160 40 11 20 Yes; Universal PID controller with integrated optimization
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_3Step	20 160 40 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
 per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp 	20 160 40 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_3Step • PID-Temp Counting and measuring • High-speed counter	20 160 40 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_3Step • PID-Temp Counting and measuring • High-speed counter	20 160 40 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_3Step • PID-Temp Counting and measuring • High-speed counter Ambient conditions	20 160 40 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_3Step • PID-Temp Counting and measuring • High-speed counter Ambient conditions Ambient temperature during operation	20 160 40 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
— per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_3Step • PID-Temp Counting and measuring • High-speed counter Ambient conditions Ambient temperature during operation • horizontal installation, min.	20 160 40 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes

Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
 Installation altitude above sea level, max. 	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
 User program protection/password protection 	Yes
 Copy protection 	Yes
Block protection	Yes
Access protection	
 protection of confidential configuration data 	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
 Protection level: Write protection for Failsafe 	No
 Protection level: Complete protection 	Yes
User administration	Yes; device-wide
programming / cycle time monitoring / header	
 lower limit 	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	135 mm
Height	130 mm
Depth	65 mm; without connection module M12 7/8 inch
Weights	
Weight, approx.	492 g; device only

last modified:

