Data sheet



SIMATIC DP, CPU 1513pro-2 PN for ET 200pro, central processing unit with work memory: 600 KB for program and 2.5 MB for data, 1st interface: PROFINET IRT with 3-port switch, 2nd interface: PROFINET RT, 25 ns bit performance, degree of protection: IP65/67, SIMATIC Memory Card required, connection module required

Figure similar

General information	
Product type designation	CPU 1513pro-2 PN
HW functional status	FS01
Firmware version	V3.1
FW update possible	Yes
Product function	
I&M data	Yes; I&M0 to I&M3
 Isochronous mode 	Yes; Via X1, with minimum OB 6x cycle of 500 μs
SysLog	Yes
Engineering with	
STEP 7 TIA Portal configurable/integrated from version	V19 (FW V3.1); with older TIA Portal versions configurable as 6ES7513-2PL00-0AB0
Configuration control	
via dataset	No
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	20.4 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms
Input current	
Current consumption (rated value)	0.22 A
Current consumption, max.	0.35 A
Inrush current, max.	0.63 A; Rated value
I²t	0.3 A ² ·s
from supply voltage 1L+, max.	0.35 A
Power	
Infeed power to the backplane bus	2.275 W
Power loss	
Power loss, typ.	3.3 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	600 kbyte
• integrated (for data)	2.5 Mbyte

Load memory	
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	,
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	25 ns
for word operations, typ.	32 ns
for fixed point arithmetic, typ.	42 ns
for floating point arithmetic, typ.	170 ns
CPU-blocks	170113
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	4 000, Blocks (OB, 1 B, 1 O, BB) and OB 13
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
Size, max.	2.5 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	
Number range	0 65 535
• Size, max.	600 kbyte
FC	
Number range	0 65 535
Size, max.	600 kbyte
OB	
• Size, max.	600 kbyte
 Number of free cycle OBs 	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
 Number of cyclic interrupt OBs 	20; With minimum OB 3x cycle of 250 μs
 Number of process alarm OBs 	50
 Number of DPV1 alarm OBs 	3
 Number of isochronous mode OBs 	1
 Number of technology synchronous alarm OBs 	2
 Number of startup OBs 	100
 Number of asynchronous error OBs 	4
 Number of synchronous error OBs 	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 216 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	

Retentivity adjustable	Yes
Retentivity dayastasic Retentivity preset	No
Local data	
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of IO Controllers	
• integrated	2
• Via CM	0
Rack	
 Modules per rack, max. 	16; Expansion width max. 1.2 m
Number of lines, max.	1
Time of day	
Clock	
Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	V
• supported	Yes
• in AS, master	Yes
in AS, deviceon Ethernet via NTP	Yes Yes
	res
Interfaces Number of PROFINET interfaces	2
Number of PROFIBUS interfaces	0
Interface	
Interface types	
RJ 45 (Ethernet)	Yes: X1 P3
Number of ports	3; 2x M12 + 1x RJ45
• integrated switch	Yes
Protocols	
• IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
 Prioritized startup 	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Of which IO devices with IRT, max.Number of connectable IO Devices for RT, max.	64 128

- of which in line, max. 128 Number of IO Devices that can be simultaneously 8; in total across all interfaces activated/deactivated, max. - Number of IO Devices per tool, max. — Updating times The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data - PROFINET Security Class Update time for IRT $250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum — for send cycle of 250 µs update time of 500 μs of the isochronous OB is decisive — for send cycle of 500 µs 500 us to 8 ms - for send cycle of 1 ms 1 ms to 16 ms - for send cycle of 2 ms 2 ms to 32 ms - for send cycle of 4 ms 4 ms to 64 ms — With IRT and parameterization of "odd" send cycles Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s ... 3 Update time for RT — for send cycle of 250 μs 250 µs to 128 ms — for send cycle of 500 µs 500 µs to 256 ms - for send cycle of 1 ms 1 ms to 512 ms - for send cycle of 2 ms 2 ms to 512 ms - for send cycle of 4 ms 4 ms to 512 ms **PROFINET IO Device** Services Isochronous mode Nο - IRT Yes — PROFlenergy Yes; per user program - Shared device Yes - Number of IO Controllers with shared device, max. - activation/deactivation of I-devices Yes; per user program Asset management record Yes; per user program - PROFINET Security Class SNMP Configuration and DCP Read Only Interface types • RJ 45 (Ethernet) No Number of ports 1; 1x M12 • integrated switch Nο Protocols • IP protocol Yes: IPv4 • PROFINET IO Controller Yes • PROFINET IO Device Yes • SIMATIC communication Yes • Open IE communication Yes; Optionally also encrypted Web server Yes Media redundancy No **PROFINET IO Controller** Services - Isochronous mode No Nο - Direct data exchange — IRT — PROFlenergy Yes; per user program - Prioritized startup - Number of connectable IO Devices, max. 32; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET - Number of connectable IO Devices for RT, max. 32 - of which in line, max — Number of IO Devices that can be simultaneously 8: in total across all interfaces activated/deactivated, max. - Number of IO Devices per tool, max. - Updating times The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data

DDOFWET O. W. O.	
— PROFINET Security Class	1
Update time for RT	4 4 70
— for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services	
— Isochronous mode	No
— IRT	No
— PROFlenergy	Yes; per user program
 Prioritized startup 	No
— Shared device	Yes
 Number of IO Controllers with shared device, max. 	4
 activation/deactivation of I-devices 	Yes; per user program
 Asset management record 	Yes; per user program
— PROFINET Security Class	SNMP Configuration and DCP Read Only
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
 Autocrossing 	Yes
 Industrial Ethernet status LED 	Yes
Protocols	
PROFIsafe	No
Number of connections	
Number of connections, max.	128; Via integrated interfaces of the CPU
Number of connections reserved for ES/HMI/web	10
 Number of connections via integrated interfaces 	128
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	,
— Media redundancy	Yes; only via 1st interface (X1)
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager;
IVII VI	MRP Client
 MRP interconnection, supported 	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
 Switchover time on line break, typ. 	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
S7 communication, as server	Yes
S7 communication, as server S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	200 Staine Help (Of Communication, abor data 3126)
TCP/IP	Yes
— Data length, max.	64 kbyte
— several passive connections per port, supported	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	
1100	64 kbyte
• UDP	Yes
— Data length, max.	Yes 2 kbyte; 1 472 bytes for UDP broadcast
— Data length, max.— UDP multicast	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits
— Data length, max.— UDP multicast• DHCP	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits Yes
— Data length, max.— UDP multicast	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits
— Data length, max.— UDP multicast• DHCP	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits Yes
— Data length, max.— UDP multicast• DHCP• DNS	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits Yes Yes
 — Data length, max. — UDP multicast • DHCP • DNS • SNMP 	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits Yes Yes Yes
 — Data length, max. — UDP multicast • DHCP • DNS • SNMP • DCP 	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits Yes Yes Yes Yes Yes
 — Data length, max. — UDP multicast • DHCP • DNS • SNMP • DCP • LLDP 	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits Yes Yes Yes Yes Yes Yes
 — Data length, max. — UDP multicast • DHCP • DNS • SNMP • DCP • LLDP • Encryption 	Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; max. 78 multicast circuits Yes Yes Yes Yes Yes Yes

• web API	
Number of sessions, max.	50
— number of simultaneous HTTP calls, max.	4
— HTTP request body, max.	131 072 byte
OPC UA	,
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; Data access (read, write), method call
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
User authentication	"anonymous" or by user name & password
 Number of connections, max. 	4
 Number of nodes of the client interfaces, 	1 000
recommended max.	
 Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_L max. 	300
 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 Number of simultaneous calls of the client instructions for session management, per connection, max. 	1
 Number of simultaneous calls of the client instructions for data access, per connection, max. 	5
 Number of registerable nodes, max. 	5 000
 Number of registerable method calls of 	100
OPC_UA_MethodCall, max.	
 Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data Access (Read, Write, Subscribe), Method Call, Alarms & Condition (A&C), Custom Address Space
Application authentication	Yes
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
 User authentication 	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
— Number of sessions, max.	32
 Number of accessible variables, max. 	50 000
 Number of registerable nodes, max. 	10 000
 Number of subscriptions per session, max. 	50
— Sampling interval, min.	100 ms
— Publishing interval, min.	200 ms
 Number of server methods, max. 	20
 Number of inputs/outputs per server method, max. 	20
 Number of monitored items, recommended max. 	4 000; for 1 s sampling interval and 1 s send interval
 Number of server interfaces, max. 	10; 10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 Number of nodes for user-defined server interfaces, max. 	15 000
Alarms and Conditions	Yes
Number of program alarms	100
Number of alarms for system diagnostics	50
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
number of subscriptions, max.	250
number of tags/attributes for subscriptions, max.	2 000
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of simultaneously active program alarms	

 Number of program alarms 	
	600
 Number of alarms for system diagnostics 	100
 Number of alarms for motion technology objects 	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Profiling	Yes
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Number of variables, max.	inputorouputo, memory bito, BBS, distributed 1703, timers, counters
of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
Forcing	Yes
Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
 Number of entries, max. 	1 000
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4
Memory size per trace, max.	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
• MAINT LED	Yes
Monitoring of the supply voltage (PWR-LED)	Yes; green "24 V DC" LED
Connection display LINK TX/RX	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
- Number of qualiship Motion Control recourses for	
 Number of available Motion Control resources for technology objects 	1 120
Required Motion Control resources	40
 Required Motion Control resources per speed-controlled axis 	40 80
 Required Motion Control resources — per speed-controlled axis — per positioning axis 	80
 Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis 	80 160
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder 	80 160 80
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam 	80 160 80 20
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track 	80 160 80 20 160
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe 	80 160 80 20
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track 	80 160 80 20 160
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle 	80 160 80 20 160
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	80 160 80 20 160 40
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle 	80 160 80 20 160 40
 Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle 	80 160 80 20 160 40
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	80 160 80 20 160 40
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Ambient conditions	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_AStep PID-Temp Counting and measuring High-speed counter Ambient conditions Ambient temperature during operation	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Ambient conditions Ambient temperature during operation horizontal installation, min.	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Ambient conditions Ambient temperature during operation	80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature

 vertical installation, max. 	55 °C	
Ambient temperature during storage/transportation		
• min.	-40 °C	
• max.	70 °C	
Altitude during operation relating to sea level		
 Installation altitude above sea level, max. 	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual	
configuration / header		
configuration / programming / header		
Programming language		
— LAD	Yes	
— FBD	Yes	
— STL	Yes	
— SCL	Yes	
— GRAPH	Yes	
Know-how protection		
 User program protection/password protection 	Yes	
 Copy protection 	Yes	
Block protection	Yes	
Access protection		
 protection of confidential configuration data 	Yes	
 Protection level: Write protection 	Yes	
 Protection level: Read/write protection 	Yes	
 Protection level: Write protection for Failsafe 	No	
 Protection level: Complete protection 	Yes	
User administration	Yes; device-wide	
programming / cycle time monitoring / header		
• lower limit	adjustable minimum cycle time	
• upper limit	adjustable maximum cycle time	
Dimensions		
Width	135 mm	
Height	130 mm	
Depth	65 mm; without connection module M12 7/8 inch	
Weights		
Weight, approx.	492 g; device only	

last modified:

